

Busemann Functions in the Wasserstein Space: Existence, Closed-Forms and Applications

Clément Bonet¹, Elsa Cazelles², Lucas Drumetz³, Nicolas Courty⁴

¹Ecole Polytechnique, CMAP, Institut Polytechnique de Paris

²CNRS, Université de Toulouse, IRIT

³IMT Atlantique, Lab-STICC

⁴Université Bretagne Sud, IRISA



Imaging in Paris

07/04/2026



Motivation

Busemann function:

- Major tool in geometry ([Busemann, 1955](#); [Bridson and Haefliger, 2013](#))
- Many applications in Machine Learning ([Chami et al., 2021](#); [Ghadimi Atigh et al., 2021](#); [Bonet et al., 2023](#); [Berg et al., 2024](#))
→ PCA, Classification, Projections...
- Applications restricted to finite dimensional spaces

Space of probability distributions:

- Datasets of Distributions
→ Documents ([Kusner et al., 2015](#)), point clouds ([Geuter et al., 2025](#)), images ([Rubner et al., 2000](#)), single-cells ([Bellazzi et al., 2021](#))
→ Labeled distributions ([Alvarez-Melis and Fusi, 2020](#)), Gaussian mixtures ([Delon and Desolneux, 2020](#))...
- Rich geometry with Optimal Transport ([Ambrosio et al., 2008](#))

Table of Contents

Busemann Function in Metric Spaces

Busemann Functions in Wasserstein Space

Comparison of Labeled Datasets

Geodesic Metric space (Bridson and Haefliger, 2013)

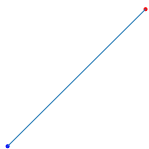
Let (X, d) be a metric space.

- Let $x, y \in X$. A continuous map $\gamma : [0, 1] \rightarrow X$ is a (constant-speed) geodesic between x and y if

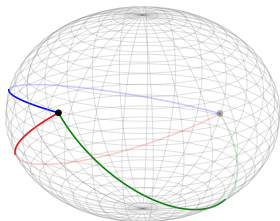
$$\begin{cases} \gamma(0) = x \\ \gamma(1) = y \\ \forall t, s \in [0, 1], d(\gamma(t), \gamma(s)) = |t - s|d(x, y) \end{cases}$$

$\rightarrow \gamma$ minimizes the length between x and y

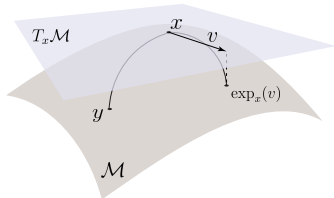
- (X, d) is a geodesic metric space if any two points are joined by a geodesic



$$X = \mathbb{R}^d, d(x, y) = \|x - y\|_2, \\ \gamma(t) = (1 - t)x + ty$$



$$X = S^{d-1}$$



$$X = \mathcal{M}, \gamma(t) = \exp_x(tv)$$

Geodesic Lines and Rays

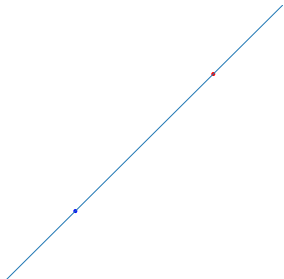
Let $\gamma : [0, 1] \rightarrow X$ be a geodesic, $\kappa = d(\gamma(0), \gamma(1))$ its speed.

- **Geodesic line:** extension of γ to \mathbb{R} such that

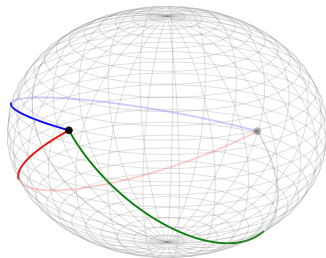
$$\forall t, s \in \mathbb{R}, d(\gamma(t), \gamma(s)) = \kappa|t - s|$$

- **Geodesic ray:** extension of γ to $[0, +\infty[$ such that

$$\forall t, s \in [0, +\infty[, d(\gamma(t), \gamma(s)) = \kappa|t - s|$$



$$\forall s, t \in \mathbb{R}, \gamma(t) = (1-t)x + ty$$



No geodesic ray or line

Sufficient Conditions for Geodesic Rays?

- Curvature $\leq 0 \iff$ for all $x \in X, t \in [0, 1]$,

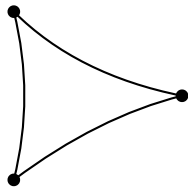
$$d^2(x, \gamma(t)) \leq (1-t)d^2(x, \gamma(0)) + td^2(x, \gamma(1)) - t(1-t)d^2(\gamma(0), \gamma(1))$$

→ geodesics are **geodesics lines**

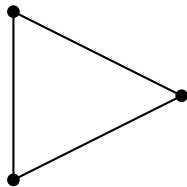
- Curvature $> 0 \iff$ for all $x \in X, t \in [0, 1]$,

$$d^2(x, \gamma(t)) > (1-t)d^2(x, \gamma(0)) + td^2(x, \gamma(1)) - t(1-t)d^2(\gamma(0), \gamma(1))$$

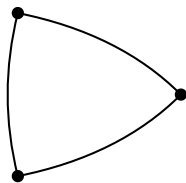
→ **no guarantees**



Negatively curved



No curvature



Positively curved

Examples of Non-Positively Curved Spaces

- **Euclidean spaces** $(\mathbb{R}^d, \|\cdot\|_2)$: $\forall x \in \mathbb{R}^d$, (parallelogram rule)

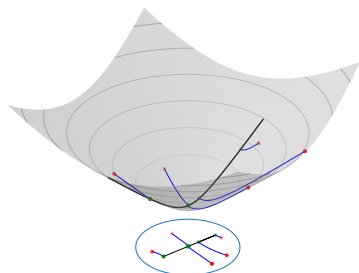
$$\|x - \gamma(t)\|_2^2 = (1-t)\|x - \gamma(0)\|_2^2 + t\|x - \gamma(1)\|_2^2 - t(1-t)\|\gamma(0) - \gamma(1)\|_2^2$$

- **Hyperbolic spaces**: $\mathbb{L}^d = \{(x_0, \dots, x_d) \in \mathbb{R}^{d+1}, \langle x, x \rangle_{\mathbb{L}} = -1, x_0 > 0\}$,

$$d_{\mathbb{L}}(x, y) = \operatorname{arccosh}(-\langle x, y \rangle_{\mathbb{L}}), \quad \langle x, y \rangle_{\mathbb{L}} = -x_0 y_0 + \sum_{i=1}^d x_i y_i$$

Geodesic: $\forall t \in \mathbb{R}, \gamma(t) = \cosh(t\|v\|_{\mathbb{L}})x + \sinh(t\|v\|_{\mathbb{L}})\frac{v}{\|v\|_{\mathbb{L}}}$

→ (constant) negative curvature



Busemann Function

Let (X, d) be a geodesic metric space and $\gamma : [0, +\infty[\rightarrow X$ be a geodesic ray.

Busemann function associated to γ :

$$\begin{aligned}\forall x \in X, B^\gamma(x) &= \lim_{t \rightarrow +\infty} d(x, \gamma(t)) - d(\gamma(0), \gamma(t)) \\ &= \lim_{t \rightarrow +\infty} d(x, \gamma(t)) - t \cdot d(\gamma(0), \gamma(1))\end{aligned}$$

Busemann Function

Let (X, d) be a geodesic metric space and $\gamma : [0, +\infty[\rightarrow X$ be a geodesic ray.

Busemann function associated to γ :

$$\begin{aligned}\forall x \in X, B^\gamma(x) &= \lim_{t \rightarrow +\infty} d(x, \gamma(t)) - d(\gamma(0), \gamma(t)) \\ &= \lim_{t \rightarrow +\infty} d(x, \gamma(t)) - t \cdot d(\gamma(0), \gamma(1))\end{aligned}$$

For $X = \mathbb{R}^d$, $\gamma(t) = x_0 + tv$, $x_0, v = x_1 - x_0 \in \mathbb{R}^d$,

$$\begin{aligned}d(x, \gamma(t)) - d(\gamma(0), \gamma(t)) &= \|x - x_0 - tv\|_2 - \|x_0 - x_0 - tv\|_2 \\ &= t\|v\|_2 \sqrt{1 - \frac{2}{t\|v\|_2^2} \langle v, x - x_0 \rangle + o(t^{-1})} - t\|v\|_2 \\ &= t\|v\|_2 \left(1 - \frac{1}{t\|v\|_2^2} \langle v, x - x_0 \rangle + o(t^{-1}) \right) - t\|v\|_2 \\ &= - \left\langle x - x_0, \frac{v}{\|v\|_2} \right\rangle + o(1)\end{aligned}$$

$$\rightarrow B^\gamma(x) = - \left\langle x - x_0, \frac{v}{\|v\|_2} \right\rangle$$

Busemann Function on \mathbb{R}^d

On \mathbb{R}^d : for $\gamma(t) = x_0 + tv$ with $x_0, v \in \mathbb{R}^d$,

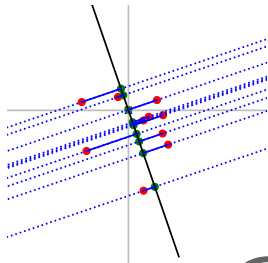
$$\forall x \in \mathbb{R}^d, B^\gamma(x) = - \left\langle x - x_0, \frac{v}{\|v\|_2} \right\rangle$$

- $B^\gamma(x)$: coincides with the coordinate of the geodesic projection (up to a sign)

$$t = \operatorname{argmin}_{s \in \mathbb{R}} \|x - (x_0 + sv)\|_2^2 = \left\langle x - x_0, \frac{v}{\|v\|_2} \right\rangle$$

→ Projection: $\gamma(-B^\gamma(x))$

- Level sets of B^γ are hyperplanes orthogonal to v



Busemann Function on \mathbb{R}^d

On \mathbb{R}^d : for $\gamma(t) = x_0 + tv$ with $x_0, v \in \mathbb{R}^d$,

$$\forall x \in \mathbb{R}^d, B^\gamma(x) = - \left\langle x - x_0, \frac{v}{\|v\|_2} \right\rangle$$

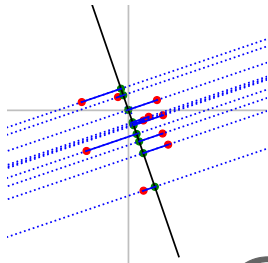
- $B^\gamma(x)$: coincides with the coordinate of the geodesic projection (up to a sign)

$$t = \operatorname{argmin}_{s \in \mathbb{R}} \|x - (x_0 + sv)\|_2^2 = \left\langle x - x_0, \frac{v}{\|v\|_2} \right\rangle$$

→ Projection: $\gamma(-B^\gamma(x))$

- Level sets of B^γ are hyperplanes orthogonal to v

→ **What about on other spaces?**



Busemann Function on Hyperbolic Space

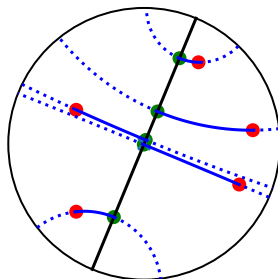
Let $x^0 = (1, 0, \dots, 0) \in \mathbb{R}^{d+1}$, $v \in T_{x^0} \mathbb{L}^d \cap S^d$,

$$\forall x \in \mathbb{L}^d, B^\gamma(x) = \log(-\langle x, x^0 + v \rangle_{\mathbb{L}})$$

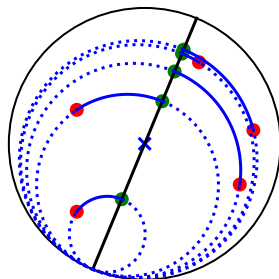
→ different from geodesic projection ([Bonet et al., 2023](#))

Horospheres: Levels sets of B^γ : $(B^\gamma)^{-1}(\{t\})$ for all $t \in \mathbb{R}$

→ Second generalization of hyperplanes



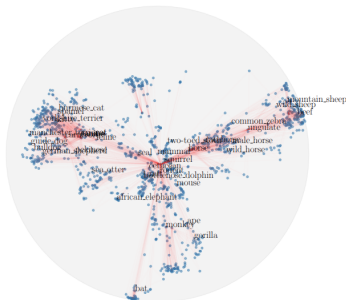
Projections along geodesics
submanifolds



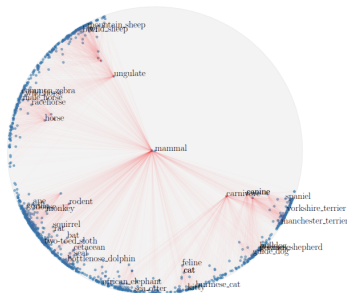
Projections along
horospheres

Applications in Machine Learning

- Busemann used as a projection
 - HoroPCA (Chami et al., 2021)
 - Project on a geodesic subspace along horospheres



(a) PGA (average distortion: 0.534)

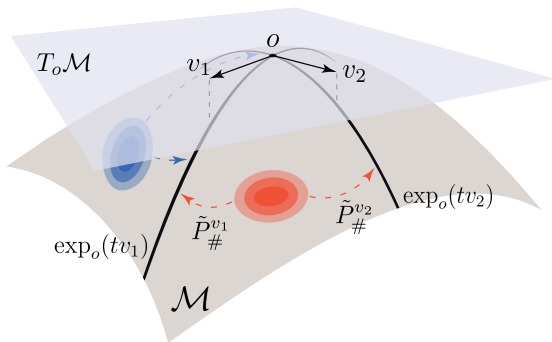


(b) HOROPCA (average distortion: 0.078)

From (Chami et al., 2021)

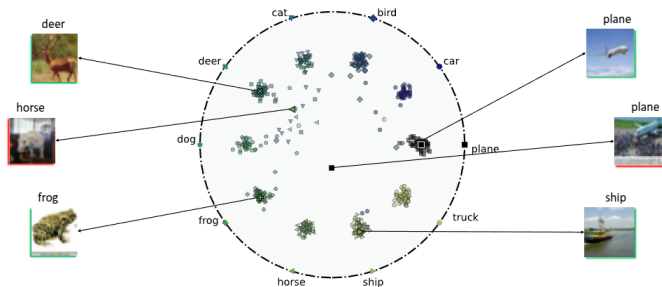
Applications in Machine Learning

- Busemann used as a projection
 - HoroPCA (Chami et al., 2021)
 - Project on a geodesic subspace along horospheres
 - Sliced-Wasserstein on Cartan-Hadamard manifolds (Bonet et al., 2023, 2025a)
 - Project on geodesics with the Busemann function



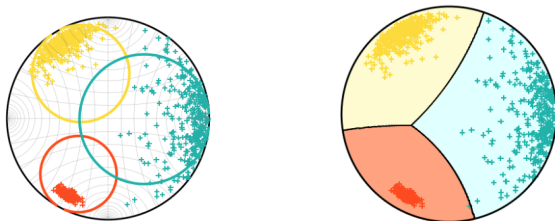
Applications in Machine Learning

- Busemann used as a projection
 - HoroPCA (Chami et al., 2021)
 - Project on a geodesic subspace along horospheres
 - Sliced-Wasserstein on Cartan-Hadamard manifolds (Bonet et al., 2023, 2025a)
 - Project on geodesics with the Busemann function
- Busemann used for alignments
 - Embedding with prototypes (Ghadimi Atigh et al., 2021)



Applications in Machine Learning

- Busemann used as a projection
 - HoroPCA (Chami et al., 2021)
 - Project on a geodesic subspace along horospheres
 - Sliced-Wasserstein on Cartan-Hadamard manifolds (Bonet et al., 2023, 2025a)
 - Project on geodesics with the Busemann function
- Busemann used for alignments
 - Embedding with prototypes (Ghadimi Atigh et al., 2021)
- Busemann used for classification (Fan et al., 2023; Doorenbos et al., 2024; Berg et al., 2024, 2025)
 - SVM, Random Forests, Logistic Regression...



From (Berg et al., 2024)

Table of Contents

Busemann Function in Metric Spaces

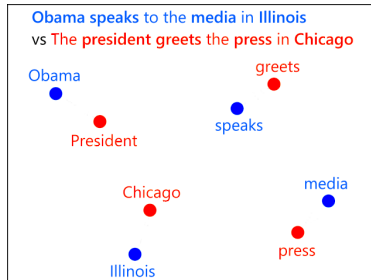
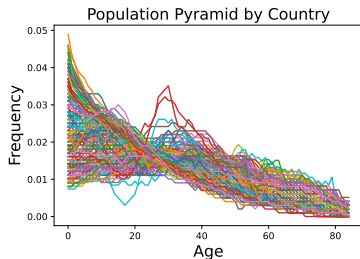
Busemann Functions in Wasserstein Space

Comparison of Labeled Datasets

Datasets of Distributions

Examples

- Histograms (e.g. age distributions of countries, financial assets...)
- Documents: distributions of words ([Kusner et al., 2015](#))
- Cells: distributions of genes ([Bellazzi et al., 2021](#))
- Embedding of words in Gaussian distributions ([Vilnis and McCallum, 2015](#))



Wasserstein Geometry (Ambrosio et al., 2008)

Definition (Wasserstein distance)

Let $\mu, \nu \in \mathcal{P}_2(\mathbb{R}^d)$ and denote by $\Pi(\mu, \nu)$ the set of coupling between μ, ν . Then, the Wasserstein distance is

$$W_2^2(\mu, \nu) = \inf_{\gamma \in \Pi(\mu, \nu)} \int \|x - y\|_2^2 d\gamma(x, y),$$

with $\Pi(\mu, \nu) = \{\gamma \in \mathcal{P}_2(\mathbb{R}^d \times \mathbb{R}^d), \pi_{\#}^1 \gamma = \mu, \pi_{\#}^2 \gamma = \nu\}$, $\pi^1 : (x, y) \mapsto x$,
 $\pi^2 : (x, y) \mapsto y$

Reminder: For $T : \mathbb{R}^d \rightarrow \mathbb{R}^p$ measurable, $X \sim \mu \implies T(X) \sim T_{\#}\mu$

Wasserstein Geometry (Ambrosio et al., 2008)

Definition (Wasserstein distance)

Let $\mu, \nu \in \mathcal{P}_2(\mathbb{R}^d)$ and denote by $\Pi(\mu, \nu)$ the set of coupling between μ, ν . Then, the Wasserstein distance is

$$W_2^2(\mu, \nu) = \inf_{\gamma \in \Pi(\mu, \nu)} \int \|x - y\|_2^2 d\gamma(x, y),$$

with $\Pi(\mu, \nu) = \{\gamma \in \mathcal{P}_2(\mathbb{R}^d \times \mathbb{R}^d), \pi_{\#}^1 \gamma = \mu, \pi_{\#}^2 \gamma = \nu\}$, $\pi^1 : (x, y) \mapsto x$, $\pi^2 : (x, y) \mapsto y$

Remainder: For $T : \mathbb{R}^d \rightarrow \mathbb{R}^p$ measurable, $X \sim \mu \implies T(X) \sim T_{\#}\mu$

Properties:

- W_2 distance, $(\mathcal{P}_2(\mathbb{R}^d), W_2)$: Wasserstein space
- $W_2(\delta_x, \delta_y) = \|x - y\|_2$
- Riemannian structure
- Geodesic metric space

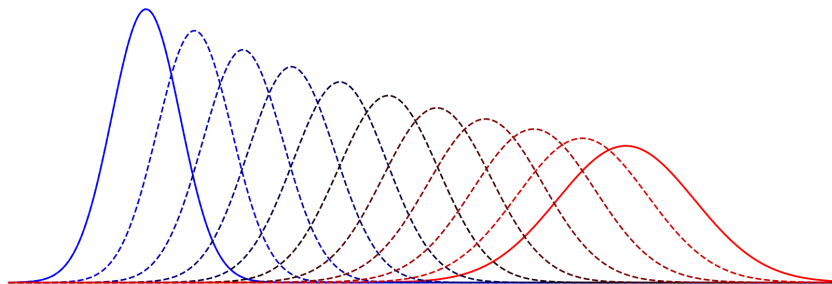
Geodesics in Wasserstein Space

Let $\Pi_o(\mu, \nu) = \{\gamma, \gamma \in \operatorname{argmin}_{\gamma \in \Pi(\mu, \nu)} \int \|x - y\|_2^2 d\gamma(x, y)\}$

Geodesics

For $\mu_0, \mu_1 \in \mathcal{P}_2(\mathbb{R}^d)$, geodesic = displacement interpolation:

$$\forall t \in [0, 1], \mu_t = ((1-t)\pi^1 + t\pi^2)_{\#} \gamma \quad \text{for } \gamma \in \Pi_o(\mu_0, \mu_1)$$



Geodesics in Wasserstein Space

Let $\Pi_o(\mu, \nu) = \{\gamma, \gamma \in \operatorname{argmin}_{\gamma \in \Pi(\mu, \nu)} \int \|x - y\|_2^2 d\gamma(x, y)\}$

Geodesics

For $\mu_0, \mu_1 \in \mathcal{P}_2(\mathbb{R}^d)$, geodesic = displacement interpolation:

$$\forall t \in [0, 1], \mu_t = ((1-t)\pi^1 + t\pi^2)_{\#} \gamma \quad \text{for } \gamma \in \Pi_o(\mu_0, \mu_1)$$

For all $\nu \in \mathcal{P}_2(\mathbb{R}^d)$, $t \in [0, 1]$, (Ambrosio et al., 2008)

$$W_2^2(\mu_t, \nu) \geq (1-t)W_2^2(\mu_0, \nu) + tW_2^2(\mu_1, \nu) - t(1-t)W_2^2(\mu_0, \mu_1)$$

→ Positively curved space (PC Space)

Geodesics in Wasserstein Space

Let $\Pi_o(\mu, \nu) = \{\gamma, \gamma \in \operatorname{argmin}_{\gamma \in \Pi(\mu, \nu)} \int \|x - y\|_2^2 d\gamma(x, y)\}$

Geodesics

For $\mu_0, \mu_1 \in \mathcal{P}_2(\mathbb{R}^d)$, geodesic = displacement interpolation:

$$\forall t \in [0, 1], \mu_t = ((1-t)\pi^1 + t\pi^2)_{\#} \gamma \quad \text{for } \gamma \in \Pi_o(\mu_0, \mu_1)$$

For all $\nu \in \mathcal{P}_2(\mathbb{R}^d)$, $t \in [0, 1]$, ([Ambrosio et al., 2008](#))

$$W_2^2(\mu_t, \nu) \geq (1-t)W_2^2(\mu_0, \nu) + tW_2^2(\mu_1, \nu) - t(1-t)W_2^2(\mu_0, \mu_1)$$

→ Positively curved space (PC Space)

By ([Zhu et al., 2021](#)): always at least one geodesic ray starting from μ_0

→ Conditions to extend $t \mapsto \mu_t$ to \mathbb{R}_+ ?

1D Wasserstein Space

Let $\mu, \nu \in \mathcal{P}_2(\mathbb{R})$,

- Cumulative distribution function:

$$\forall t \in \mathbb{R}, F_\mu(t) = \mu([-\infty, t]) = \int \mathbb{1}_{]-\infty, t]}(x) d\mu(x)$$

- Quantile function:

$$\forall u \in [0, 1], F_\mu^{-1}(u) = \inf \{x \in \mathbb{R}, F_\mu(x) \geq u\}$$

1D Wasserstein Distance

The optimal coupling is $\gamma^* = (F_\mu^{-1}, F_\nu^{-1})_\# \text{Unif}([0, 1])$, and

$$W_2^2(\mu, \nu) = \int_0^1 |F_\mu^{-1}(u) - F_\nu^{-1}(u)|^2 du = \|F_\mu^{-1} - F_\nu^{-1}\|_{L^2([0,1])}^2$$

1D Wasserstein Space

Let $\mu, \nu \in \mathcal{P}_2(\mathbb{R})$,

- Cumulative distribution function:

$$\forall t \in \mathbb{R}, F_\mu(t) = \mu([-\infty, t]) = \int \mathbb{1}_{]-\infty, t]}(x) \, d\mu(x)$$

- Quantile function:

$$\forall u \in [0, 1], F_\mu^{-1}(u) = \inf \{x \in \mathbb{R}, F_\mu(x) \geq u\}$$

1D Wasserstein Distance

The optimal coupling is $\gamma^* = (F_\mu^{-1}, F_\nu^{-1})_\# \text{Unif}([0, 1])$, and

$$W_2^2(\mu, \nu) = \int_0^1 |F_\mu^{-1}(u) - F_\nu^{-1}(u)|^2 \, du = \|F_\mu^{-1} - F_\nu^{-1}\|_{L^2([0, 1])}^2$$

Geodesic between μ and ν : $\forall t \in [0, 1]$,

$$\mu_t = ((1-t)\pi^1 + t\pi^2)_\# \gamma^* = ((1-t)F_\mu^{-1} + tF_\nu^{-1})_\# \text{Unif}([0, 1])$$

$$\rightarrow F_t^{-1} = (1-t)F_\mu^{-1} + tF_\nu^{-1}$$

Geodesic Rays in 1D Wasserstein Space

For $\mu_0, \mu_1 \in \mathcal{P}_2(\mathbb{R})$, quantile F_t^{-1} of the geodesic $t \mapsto \mu_t$ characterized as

$$\forall t \in [0, 1], F_t^{-1} = (1 - t)F_0^{-1} + tF_1^{-1} = F_0^{-1} + t(F_1^{-1} - F_0^{-1}).$$

- For all $t, s \in \mathbb{R}$,

$$\|F_t^{-1} - F_s^{-1}\|_{L^2([0,1])}^2 = (t - s)^2 \|F_0^{-1} - F_1^{-1}\|_{L^2([0,1])}^2$$

→ ok if F_t^{-1}, F_s^{-1} quantile functions, i.e. non-decreasing and left-continuous

Geodesic Rays in 1D Wasserstein Space

For $\mu_0, \mu_1 \in \mathcal{P}_2(\mathbb{R})$, quantile F_t^{-1} of the geodesic $t \mapsto \mu_t$ characterized as

$$\forall t \in [0, 1], F_t^{-1} = (1 - t)F_0^{-1} + tF_1^{-1} = F_0^{-1} + t(F_1^{-1} - F_0^{-1}).$$

- For all $t, s \in \mathbb{R}$,

$$\|F_t^{-1} - F_s^{-1}\|_{L^2([0,1])}^2 = (t - s)^2 \|F_0^{-1} - F_1^{-1}\|_{L^2([0,1])}^2$$

→ ok if F_t^{-1}, F_s^{-1} quantile functions, i.e. non-decreasing and left-continuous

- For all $t \geq 0, 0 < m < m' < 1$,

$$\begin{aligned} F_t^{-1}(m) - F_t^{-1}(m') &= F_0^{-1}(m) - F_0^{-1}(m') \\ &\quad + t(F_1^{-1}(m) - F_0^{-1}(m) - (F_1^{-1}(m') - F_0^{-1}(m'))) \leq 0 \end{aligned}$$

Proposition (Kloeckner, 2010)

$t \mapsto \mu_t$ is a geodesic ray if and only if $F_1^{-1} - F_0^{-1}$ is non-decreasing.

Illustrations - 1D Gaussian Case

Let $\mu_0 = \mathcal{N}(m_0, \sigma_0^2)$, $\mu_1 = \mathcal{N}(m_1, \sigma_1^2)$, ϕ^{-1} quantile function of $\mathcal{N}(0, 1)$.

$$\rightarrow F_0^{-1} = m_0 + \sigma_0 \phi^{-1}, F_1^{-1} = m_1 + \sigma_1 \phi^{-1}$$

$$\rightarrow \forall t \in [0, 1], \mu_t = \mathcal{N}((1-t)m_0 + tm_1, ((1-t)\sigma_0 + t\sigma_1)^2)$$

Illustrations - 1D Gaussian Case

Let $\mu_0 = \mathcal{N}(m_0, \sigma_0^2)$, $\mu_1 = \mathcal{N}(m_1, \sigma_1^2)$, ϕ^{-1} quantile function of $\mathcal{N}(0, 1)$.

$$\rightarrow F_0^{-1} = m_0 + \sigma_0 \phi^{-1}, F_1^{-1} = m_1 + \sigma_1 \phi^{-1}$$

$$\rightarrow \forall t \in [0, 1], \mu_t = \mathcal{N}((1-t)m_0 + tm_1, ((1-t)\sigma_0 + t\sigma_1)^2)$$

For all $0 < m < m' < 1$,

$$((F_1^{-1} - F_0^{-1})(m')) - ((F_1^{-1} - F_0^{-1})(m)) = (\sigma_1 - \sigma_0)(\phi^{-1}(m') - \phi^{-1}(m)) \geq 0$$

$$\iff \sigma_1 \geq \sigma_0$$

$t \mapsto \mu_t$ is a geodesic ray if and only if $\sigma_1 \geq \sigma_0$.

Illustrations - 1D Gaussian Case

Let $\mu_0 = \mathcal{N}(m_0, \sigma_0^2)$, $\mu_1 = \mathcal{N}(m_1, \sigma_1^2)$, ϕ^{-1} quantile function of $\mathcal{N}(0, 1)$.

$$\rightarrow F_0^{-1} = m_0 + \sigma_0 \phi^{-1}, F_1^{-1} = m_1 + \sigma_1 \phi^{-1}$$

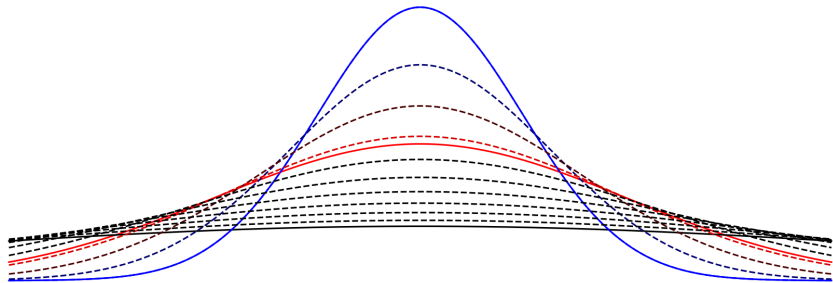
$$\rightarrow \forall t \in [0, 1], \mu_t = \mathcal{N}((1-t)m_0 + tm_1, ((1-t)\sigma_0 + t\sigma_1)^2)$$

For all $0 < m < m' < 1$,

$$((F_1^{-1} - F_0^{-1})(m') - (F_1^{-1} - F_0^{-1})(m)) = (\sigma_1 - \sigma_0)(\phi^{-1}(m') - \phi^{-1}(m)) \geq 0$$

$$\iff \sigma_1 \geq \sigma_0$$

$t \mapsto \mu_t$ is a geodesic ray if and only if $\sigma_1 \geq \sigma_0$.



Illustrations - 1D Gaussian Case

Let $\mu_0 = \mathcal{N}(m_0, \sigma_0^2)$, $\mu_1 = \mathcal{N}(m_1, \sigma_1^2)$, ϕ^{-1} quantile function of $\mathcal{N}(0, 1)$.

$$\rightarrow F_0^{-1} = m_0 + \sigma_0 \phi^{-1}, F_1^{-1} = m_1 + \sigma_1 \phi^{-1}$$

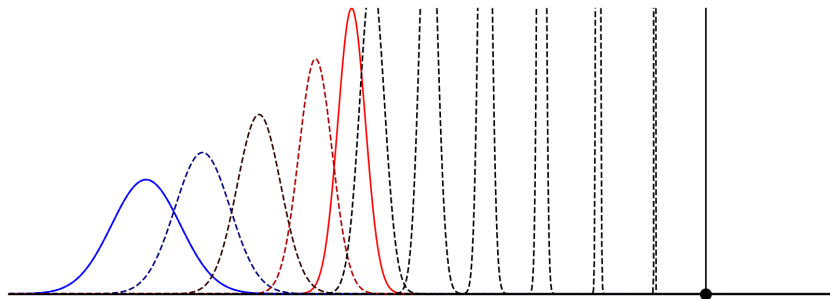
$$\rightarrow \forall t \in [0, 1], \mu_t = \mathcal{N}((1-t)m_0 + tm_1, ((1-t)\sigma_0 + t\sigma_1)^2)$$

For all $0 < m < m' < 1$,

$$((F_1^{-1} - F_0^{-1})(m') - (F_1^{-1} - F_0^{-1})(m)) = (\sigma_1 - \sigma_0)(\phi^{-1}(m') - \phi^{-1}(m)) \geq 0$$

$$\iff \sigma_1 \geq \sigma_0$$

$t \mapsto \mu_t$ is a geodesic ray if and only if $\sigma_1 \geq \sigma_0$.



Illustrations - Starting from a Dirac

Let $x_0 \in \mathbb{R}$, $\mu_0 = \delta_{x_0}$, $F_0^{-1}(p) = x_0$ for all $1 \geq p > 0$.

→ For all $\mu_1 \in \mathcal{P}_2(\mathbb{R})$, $F_1^{-1} - F_0^{-1}$ non-decreasing

→ $\gamma^* = \mu_0 \otimes \mu_1$, $\mu_t = ((1-t)x_0 + t\text{Id})_{\#}\mu_1$

For all $\mu_1 \in \mathcal{P}_2(\mathbb{R})$, $t \mapsto \mu_t$ is a geodesic ray.



Illustrations - Starting from a Dirac

Let $x_0 \in \mathbb{R}$, $\mu_0 = \delta_{x_0}$, $F_0^{-1}(p) = x_0$ for all $1 \geq p > 0$.

→ For all $\mu_1 \in \mathcal{P}_2(\mathbb{R})$, $F_1^{-1} - F_0^{-1}$ non-decreasing

→ $\gamma^* = \mu_0 \otimes \mu_1$, $\mu_t = ((1-t)x_0 + t\text{Id})_{\#}\mu_1$

For all $\mu_1 \in \mathcal{P}_2(\mathbb{R})$, $t \mapsto \mu_t$ is a geodesic ray.



Illustrations - Starting from a Dirac

Let $x_0 \in \mathbb{R}$, $\mu_0 = \delta_{x_0}$, $F_0^{-1}(p) = x_0$ for all $1 \geq p > 0$.

→ For all $\mu_1 \in \mathcal{P}_2(\mathbb{R})$, $F_1^{-1} - F_0^{-1}$ non-decreasing

→ $\gamma^* = \mu_0 \otimes \mu_1$, $\mu_t = ((1-t)x_0 + t\text{Id})_{\#}\mu_1$

For all $\mu_1 \in \mathcal{P}_2(\mathbb{R})$, $t \mapsto \mu_t$ is a geodesic ray.

→ extends to \mathbb{R}^d (Bertrand and Kloeckner, 2016, Lemma 2.1)

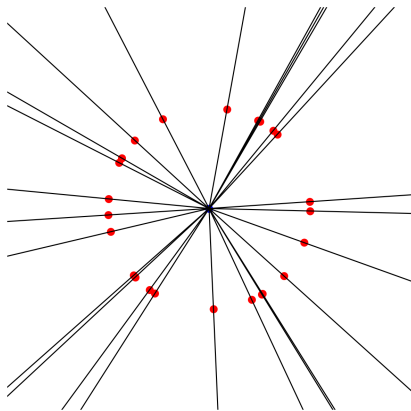


Illustration - Discrete Distributions

Let $x_1 < \dots < x_n$, $y_1 < \dots < y_n$, $\mu_0 = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$, $\mu_1 = \frac{1}{n} \sum_{i=1}^n \delta_{y_i}$.

$t \mapsto \mu_t$ is a geodesic ray if and only if for all $j > i$, $y_i - x_i \leq y_j - x_j$.

Illustration - Discrete Distributions

Let $x_1 < \dots < x_n$, $y_1 < \dots < y_n$, $\mu_0 = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$, $\mu_1 = \frac{1}{n} \sum_{i=1}^n \delta_{y_i}$.

$t \mapsto \mu_t$ is a geodesic ray if and only if for all $j > i$, $y_i - x_i \leq y_j - x_j$.

$$\mu_0 = \frac{1}{2}\delta_{-2} + \frac{1}{2}\delta_0, \quad \mu_1 = \frac{1}{2}\delta_{-1} + \frac{1}{2}\delta_{1.5}$$

$\rightarrow y_1 - x_1 = 1 < y_2 - x_2 = 1.5$

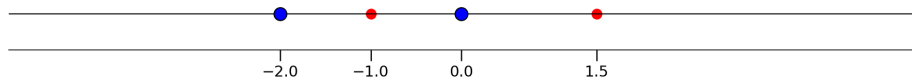


Illustration - Discrete Distributions

Let $x_1 < \dots < x_n$, $y_1 < \dots < y_n$, $\mu_0 = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$, $\mu_1 = \frac{1}{n} \sum_{i=1}^n \delta_{y_i}$.

$t \mapsto \mu_t$ is a geodesic ray if and only if for all $j > i$, $y_i - x_i \leq y_j - x_j$.

$$\mu_0 = \frac{1}{2}\delta_{-2} + \frac{1}{2}\delta_0, \quad \mu_1 = \frac{1}{2}\delta_{-1} + \frac{1}{2}\delta_{1.5}$$

$\rightarrow y_1 - x_1 = 1 < y_2 - x_2 = 1.5$

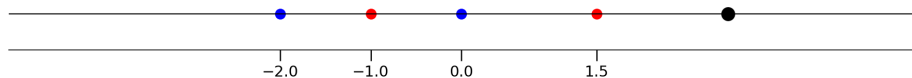


Illustration - Discrete Distributions

Let $x_1 < \dots < x_n$, $y_1 < \dots < y_n$, $\mu_0 = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$, $\mu_1 = \frac{1}{n} \sum_{i=1}^n \delta_{y_i}$.

$t \mapsto \mu_t$ is a geodesic ray if and only if for all $j > i$, $y_i - x_i \leq y_j - x_j$.

$$\mu_0 = \frac{1}{2}\delta_0 + \frac{1}{2}\delta_4, \quad \mu_1 = \frac{1}{2}\delta_{-1} + \frac{1}{2}\delta_{1.5}$$

$\rightarrow y_1 - x_1 = -1 > y_2 - x_2 = -2.5$

Not a ray (particles cross at $t > 0$)

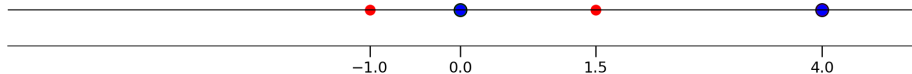


Illustration - Discrete Distributions

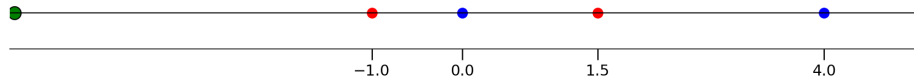
Let $x_1 < \dots < x_n$, $y_1 < \dots < y_n$, $\mu_0 = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$, $\mu_1 = \frac{1}{n} \sum_{i=1}^n \delta_{y_i}$.

$t \mapsto \mu_t$ is a geodesic ray if and only if for all $j > i$, $y_i - x_i \leq y_j - x_j$.

$$\mu_0 = \frac{1}{2}\delta_0 + \frac{1}{2}\delta_4, \quad \mu_1 = \frac{1}{2}\delta_{-1} + \frac{1}{2}\delta_{1.5}$$

$\rightarrow y_1 - x_1 = -1 > y_2 - x_2 = -2.5$

Not a ray (particles cross at $t > 0$)



Geodesic Rays in Brenier's Setting

Proposition (Brenier's Theorem (Brenier, 1991))

$\mu_0 \ll \text{Leb} \implies$ *Optimal coupling γ^* unique and $\gamma^* = (\text{Id}, \nabla\varphi)_\# \mu_0$ with φ convex*

In this setting:

- Geodesic between $\mu_0 \in \mathcal{P}_{2,\text{ac}}(\mathbb{R}^d)$ and $\mu_1 \in \mathcal{P}_2(\mathbb{R}^d)$ unique
- For all $t \in [0, 1]$, $\mu_t = ((1-t)\text{Id} + t\text{T})_\# \mu_0$ with $\text{T}_\# \mu_0 = \mu_1$, $\text{T} = \nabla\varphi$, φ convex

Geodesic Rays in Brenier's Setting

Proposition (Brenier's Theorem (Brenier, 1991))

$\mu_0 \ll \text{Leb} \implies$ Optimal coupling γ^* unique and $\gamma^* = (\text{Id}, \nabla\varphi)_{\#}\mu_0$ with φ convex

In this setting:

- Geodesic between $\mu_0 \in \mathcal{P}_{2,\text{ac}}(\mathbb{R}^d)$ and $\mu_1 \in \mathcal{P}_2(\mathbb{R}^d)$ unique
- For all $t \in [0, 1]$, $\mu_t = ((1-t)\text{Id} + t\text{T})_{\#}\mu_0$ with $\text{T}_{\#}\mu_0 = \mu_1$, $\text{T} = \nabla\varphi$, φ convex
- If $t \mapsto \mu_t$ is a geodesic ray:

$$\begin{aligned}\forall s \geq 0, \quad W_2^2(\mu_s, \mu_0) &= s^2 W_2^2(\mu_1, \mu_0) \\ &= \int \|s(x - \nabla\varphi(x))\|_2^2 \, d\mu_0(x) \\ &= \int \|x - (1-s)x - s\nabla\varphi(x)\|_2^2 \, d\mu_0(x)\end{aligned}$$

$\rightarrow (1-s)x + s\nabla\varphi(x) = \nabla(x \mapsto (1-s)\frac{\|x\|_2^2}{2} + s\varphi(x))(x)$ must be the gradient of a convex function for all $s \geq 0$

\rightarrow true if and only if $\varphi - \frac{\|x\|_2^2}{2}$ convex

Geodesic Rays in Brenier's Setting

Let $\mu_0 \in \mathcal{P}_{2,\text{ac}}(\mathbb{R}^d)$, $\mu_1 \in \mathcal{P}_2(\mathbb{R}^d)$, $\mu_1 = (\nabla\varphi)_\# \mu_0$, φ convex.
 $\rightarrow t \mapsto \mu_t$ geodesic ray if and only if φ 1-strongly convex

Examples

- 1D Gaussian: Let $\mu_0 = \mathcal{N}(m_0, \sigma_0^2)$, $\mu_1 = \mathcal{N}(m_1, \sigma_1^2)$, $T(x) = \frac{\sigma_1}{\sigma_0}(x - m_0) + m_1$

$$T'(x) - 1 \geq 0 \iff \sigma_1 \geq \sigma_0$$

- General Gaussian: Let $\mu_0 = \mathcal{N}(m_0, \Sigma_0)$, $\mu_1 = \mathcal{N}(m_1, \Sigma_1)$,
 $T(x) = A(x - m_0) + m_1$ with $A = \Sigma_0^{-\frac{1}{2}} (\Sigma_0^{\frac{1}{2}} \Sigma_1 \Sigma_0^{\frac{1}{2}})^{\frac{1}{2}} \Sigma_0^{-\frac{1}{2}}$,

$$\nabla T(x) - I_d \succeq 0 \iff (\Sigma_0^{\frac{1}{2}} \Sigma_1 \Sigma_0^{\frac{1}{2}})^{\frac{1}{2}} \succeq \Sigma_0$$

Busemann Function in the Wasserstein Space

Let $\mu_0 \in \mathcal{P}_2(\mathbb{R}^d)$, $t \mapsto \mu_t$ a geodesic ray starting from μ_0

Busemann function in $(\mathcal{P}_2(\mathbb{R}^d), W_2)$:

$$\forall \nu \in \mathcal{P}_2(\mathbb{R}^d), B^\mu(\nu) = \lim_{t \rightarrow +\infty} W_2(\mu_t, \nu) - \kappa_\mu t,$$

with $\kappa_\mu = W_2(\mu_0, \mu_1)$.

→ Computation?

Computing the Busemann Function

Define $\Gamma(\mu_0, \mu_1, \nu) = \{\tilde{\gamma} \in \Pi(\mu_0, \mu_1, \nu), \pi_{\#}^{1,2}\tilde{\gamma} \in \Pi_o(\mu_0, \mu_1)\}$

- General case:

$$B^\mu(\nu) = \inf_{\tilde{\gamma} \in \Gamma(\mu_0, \mu_1, \nu)} -\kappa_\mu^{-1} \int \langle x_1 - x_0, y - x_0 \rangle d\tilde{\gamma}(x_0, x_1, y)$$

Computing the Busemann Function

Define $\Gamma(\mu_0, \mu_1, \nu) = \{\tilde{\gamma} \in \Pi(\mu_0, \mu_1, \nu), \pi_{\#}^{1,2} \tilde{\gamma} \in \Pi_o(\mu_0, \mu_1)\}$

- General case:

$$B^\mu(\nu) = \inf_{\tilde{\gamma} \in \Gamma(\mu_0, \mu_1, \nu)} -\kappa_\mu^{-1} \int \langle x_1 - x_0, y - x_0 \rangle d\tilde{\gamma}(x_0, x_1, y)$$

- If $\mu_0 \in \mathcal{P}_{2,ac}(\mathbb{R}^d)$, $\mu_1 = (\nabla\varphi)_{\#}\mu_0$, φ 1-strongly convex:

$$B^\mu(\nu) = \inf_{\gamma \in \Pi(\mu_0, \nu)} -\kappa_\mu^{-1} \int \langle \nabla\varphi(x_0) - x_0, y - x_0 \rangle d\gamma(x_0, y)$$

→ equivalent to OT problem with cost $c(x_0, y) = \|\nabla\varphi(x_0) - x_0 - y\|_2^2$

Computing the Busemann Function

Define $\Gamma(\mu_0, \mu_1, \nu) = \{\tilde{\gamma} \in \Pi(\mu_0, \mu_1, \nu), \pi_{\#}^{1,2}\tilde{\gamma} \in \Pi_o(\mu_0, \mu_1)\}$

- General case:

$$B^\mu(\nu) = \inf_{\tilde{\gamma} \in \Gamma(\mu_0, \mu_1, \nu)} -\kappa_\mu^{-1} \int \langle x_1 - x_0, y - x_0 \rangle d\tilde{\gamma}(x_0, x_1, y)$$

- If $\mu_0 \in \mathcal{P}_{2,ac}(\mathbb{R}^d)$, $\mu_1 = (\nabla\varphi)_{\#}\mu_0$, φ 1-strongly convex:

$$B^\mu(\nu) = \inf_{\gamma \in \Pi(\mu_0, \nu)} -\kappa_\mu^{-1} \int \langle \nabla\varphi(x_0) - x_0, y - x_0 \rangle d\gamma(x_0, y)$$

- If $\mu_0 = \delta_{x_0}$, $x_0 \in \mathbb{R}^d$, $\pi_{\#}^{1,2}\tilde{\gamma} = \mu_0 \otimes \mu_1$,

$$B^\mu(\nu) = \inf_{\gamma \in \Pi(\mu_1, \nu)} -\kappa_\mu^{-1} \int \langle x_1 - x_0, y - x_0 \rangle d\gamma(x_1, y)$$

→ Equivalent to $W_2^2(\mu_1, \nu)$

→ For $\mu_1 = \delta_{x_1}$, $\theta = x_1 - x_0 \in S^{d-1}$, $\gamma(t) = x_0 + t\theta$, $B^\mu(\nu) = \int B^\gamma(y) d\nu(y)$

Computing the Busemann Function

Define $\Gamma(\mu_0, \mu_1, \nu) = \{\tilde{\gamma} \in \Pi(\mu_0, \mu_1, \nu), \pi_{\#}^{1,2}\tilde{\gamma} \in \Pi_o(\mu_0, \mu_1)\}$

- General case:

$$B^\mu(\nu) = \inf_{\tilde{\gamma} \in \Gamma(\mu_0, \mu_1, \nu)} -\kappa_\mu^{-1} \int \langle x_1 - x_0, y - x_0 \rangle d\tilde{\gamma}(x_0, x_1, y)$$

- If $\mu_0 \in \mathcal{P}_{2,ac}(\mathbb{R}^d)$, $\mu_1 = (\nabla\varphi)_{\#}\mu_0$, φ 1-strongly convex:

$$B^\mu(\nu) = \inf_{\gamma \in \Pi(\mu_0, \nu)} -\kappa_\mu^{-1} \int \langle \nabla\varphi(x_0) - x_0, y - x_0 \rangle d\gamma(x_0, y)$$

- If $\mu_0 = \delta_{x_0}$, $x_0 \in \mathbb{R}^d$, $\pi_{\#}^{1,2}\tilde{\gamma} = \mu_0 \otimes \mu_1$,

$$B^\mu(\nu) = \inf_{\gamma \in \Pi(\mu_1, \nu)} -\kappa_\mu^{-1} \int \langle x_1 - x_0, y - x_0 \rangle d\gamma(x_1, y)$$

→ Linear programs

Busemann Function in the 1D Wasserstein Space

Let $\mu_0, \mu_1 \in \mathcal{P}_2(\mathbb{R})$,

$$W_2^2(\mu_0, \mu_1) = \int_0^1 |F_0^{-1}(u) - F_1^{-1}(u)|^2 \, du = \|F_0^{-1} - F_1^{-1}\|_{L^2([0,1])}^2$$

→ Hilbert structure

Proposition (Closed-form for the Busemann function on $\mathcal{P}_2(\mathbb{R})$)

Let $(\mu_t)_{t \geq 0}$ be a unit-speed geodesic ray in $\mathcal{P}_2(\mathbb{R})$, then

$$\begin{aligned} \forall \nu \in \mathcal{P}_2(\mathbb{R}), \quad B^\mu(\nu) &= - \int_0^1 (F_1^{-1}(u) - F_0^{-1}(u))(F_\nu^{-1}(u) - F_0^{-1}(u)) \, du \\ &= - \langle F_1^{-1} - F_0^{-1}, F_\nu^{-1} - F_0^{-1} \rangle_{L^2([0,1])}. \end{aligned}$$

Example

Let $\mu_0 = \mathcal{N}(m_0, \sigma_0^2)$, $\mu_1 = \mathcal{N}(m_1, \sigma_1^2)$, $\nu = \mathcal{N}(m, \sigma^2)$,

$$B^\mu(\nu) = -(m_1 - m_0)(m - m_0) - (\sigma_1 - \sigma_0)(\sigma - \sigma_0)$$

Busemann Function on the Bures-Wasserstein Space

Let $\mu_0 = \mathcal{N}(m_0, \Sigma_0)$, $\mu_1 = \mathcal{N}(m_1, \Sigma_1)$,

$$W_2^2(\mu_0, \mu_1) = \|m_0 - m_1\|_2^2 + \text{tr} \left(\Sigma_0 + \Sigma_1 - 2(\Sigma_0^{\frac{1}{2}} \Sigma_1 \Sigma_0^{\frac{1}{2}})^{\frac{1}{2}} \right)$$

Proposition (Closed-form for the Busemann function on $BW(\mathbb{R}^d)$)

Let $(\mu_t)_{t \geq 0}$ be a unit-speed geodesic ray characterized by $\mu_0 = \mathcal{N}(m_0, \Sigma_0)$ and $\mu_1 = \mathcal{N}(m_1, \Sigma_1)$. Then, for any $\nu = \mathcal{N}(m, \Sigma)$,

$$B^\mu(\nu) = -\langle m_1 - m_0, m - m_0 \rangle + \text{tr} \left(\Sigma_0(A - I_d) \right) \\ - \text{tr} \left((\Sigma^{\frac{1}{2}} (\Sigma_0 - \Sigma_0 A - A \Sigma_0 + \Sigma_1) \Sigma^{\frac{1}{2}})^{\frac{1}{2}} \right),$$

where $A = \Sigma_0^{-\frac{1}{2}} (\Sigma_0^{\frac{1}{2}} \Sigma_1 \Sigma_0^{\frac{1}{2}})^{\frac{1}{2}} \Sigma_0^{-\frac{1}{2}}$.

Table of Contents

Busemann Function in Metric Spaces

Busemann Functions in Wasserstein Space

Comparison of Labeled Datasets

Labeled Datasets

$$\mathcal{D}_1 : \mu_1 = \frac{1}{m} \sum_{i=1}^m \delta_{(x_i^1, y_i^1)} \in \mathcal{P}(\mathbb{R}^d \times \{1, \dots, C\}),$$

$$\mathcal{D}_2 : \mu_2 = \frac{1}{m} \sum_{j=1}^m \delta_{(x_j^2, y_j^2)} \in \mathcal{P}(\mathbb{R}^d \times \{1, \dots, C\})$$

C : number of classes, n : number of sample in each class, $m = nC$

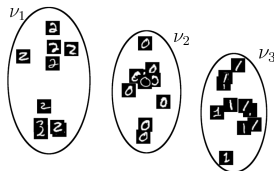
Question: how to compare datasets \mathcal{D}_1 and \mathcal{D}_2 ?



OTDD (Alvarez-Melis and Fusi, 2020)

Solution of Alvarez-Melis and Fusi (2020):

- Embed a label (a class) in $\mathcal{P}(\mathbb{R}^d)$ as $c \mapsto \nu_c^k = \frac{1}{n} \sum_{i=1}^n \delta_{x_i^k} \mathbb{1}_{\{y_i^k=c\}}$ for $k = 1, 2$

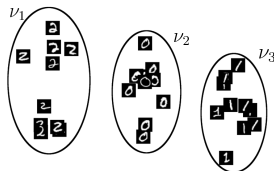


$$\rightarrow \mathcal{D}_k : \mu_k = \frac{1}{m} \sum_{i=1}^m \delta_{(x_i^k, \nu_{y_i^k}^k)} \in \mathcal{P}(\mathbb{R}^d \times \mathcal{P}(\mathbb{R}^d))$$

OTDD (Alvarez-Melis and Fusi, 2020)

Solution of Alvarez-Melis and Fusi (2020):

- Embed a label (a class) in $\mathcal{P}(\mathbb{R}^d)$ as $c \mapsto \nu_c^k = \frac{1}{n} \sum_{i=1}^n \delta_{x_i^k} \mathbb{1}_{\{y_i^k=c\}}$ for $k = 1, 2$



$$\rightarrow \mathcal{D}_k : \mu_k = \frac{1}{m} \sum_{i=1}^m \delta_{(x_i^k, y_i^k)} \in \mathcal{P}(\mathbb{R}^d \times \mathcal{P}(\mathbb{R}^d))$$

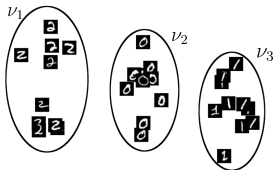
- Cost: $d((x, y), (x', y'))^2 = \|x - x'\|_2^2 + W_2^2(\nu_y, \nu_{y'})$
- Optimal transport distance:** $O(C^2 n^3 \log n + n^3 C^3 \log(nC))$

$$\text{OTDD}(\mu_1, \mu_2) = \inf_{\gamma \in \Pi(\mu_1, \mu_2)} \int d((x, y), (x', y'))^2 d\gamma((x, y), (x', y')).$$

OTDD (Alvarez-Melis and Fusi, 2020)

Solution of Alvarez-Melis and Fusi (2020):

- Embed a label (a class) in $\mathbb{R}^p \times S_p^{++}(\mathbb{R})$ as $c \mapsto \nu_c^k \approx \mathcal{N}(m_c^k, \Sigma_c^k)$ for $k = 1, 2$

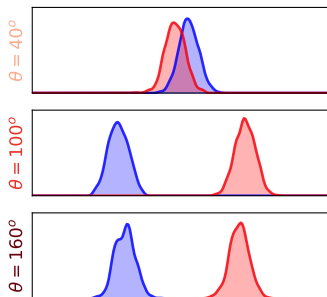
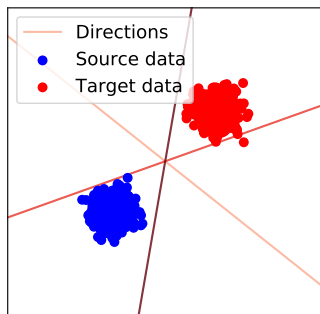


$$\rightarrow \mathcal{D}_k : \mu_k = \frac{1}{m} \sum_{i=1}^m \delta_{(x_i^k, m_{y_i^k}, \Sigma_{y_i^k})} \in \mathcal{P}(\mathbb{R}^d \times \mathbb{R}^p \times S_p^{++}(\mathbb{R}))$$

- Cost: $d((x, y), (x', y'))^2 = \|x - x'\|_2^2 + \text{BW}_2^2(\nu_y, \nu_{y'})$
- Optimal transport distance:** approximated in $O(C^2 d^3 + n^2 C^2 \log(nC)/\varepsilon^2)$

$$\text{OTDD}_\varepsilon(\mu_1, \mu_2) = \inf_{\gamma \in \Pi(\mu_1, \mu_2)} \int d((x, y), (x', y'))^2 d\gamma((x, y), (x', y')) + \varepsilon \mathcal{H}(\gamma).$$

Sliced-Wasserstein Distance



Definition (Sliced-Wasserstein (Rabin et al., 2011))

Let $\mu, \nu \in \mathcal{P}_2(\mathbb{R}^d)$,

$$\text{SW}_2^2(\mu, \nu) = \int_{S^{d-1}} W_2^2(P_{\#}^{\theta}\mu, P_{\#}^{\theta}\nu) d\lambda(\theta),$$

where $P^{\theta}(x) = \langle x, \theta \rangle$, λ uniform measure on S^{d-1} .

Sliced-Wasserstein Distance

Let $x_1, \dots, x_n, y_1, \dots, y_n \in \mathbb{R}^d$, $\alpha, \beta \in \Sigma_n$, $\mu = \sum_{i=1}^n \alpha_i \delta_{x_i}$, $\nu = \sum_{i=1}^n \beta_i \delta_{y_i}$.

Approximation via Monte-Carlo:

$$\widehat{\text{SW}}_{2,L}^2(\mu, \nu) = \frac{1}{L} \sum_{\ell=1}^L W_2^2(P_{\#}^{\theta_{\ell}} \mu, P_{\#}^{\theta_{\ell}} \nu),$$

$\theta_1, \dots, \theta_L \sim \lambda$.

→ Computational complexity: $O(Ln(\log n + d))$

Goal: Define a SW distance on $\mathcal{P}_2(\mathbb{R}^d \times \mathcal{P}_2(\mathbb{R}^d))$

Previous Methods

- Sliced-Wasserstein on $\mathcal{P}_2(X \times Y)$ (Nguyen and Ho, 2024):

- Define 2 projections $P^\theta : X \rightarrow \mathbb{R}$, $Q^\phi : Y \rightarrow \mathbb{R}$
- For $\alpha \in S^1$, define

$$\forall (x, y) \in X \times Y, P^{\alpha, \theta, \phi}(x, y) = \alpha_1 P^\theta(x) + \alpha_2 Q^\phi(y)$$

- For $\mu, \nu \in \mathcal{P}_2(X \times Y)$,

$$\text{SW}_2^2(\mu, \nu) = \int W_2^2(P_{\#}^{\alpha, \theta, \phi} \mu, P_{\#}^{\alpha, \theta, \phi} \nu) d\lambda(\alpha, \theta, \phi)$$

Previous Methods

- Sliced-Wasserstein on $\mathcal{P}_2(X \times Y)$ (Nguyen and Ho, 2024):

- Define 2 projections $P^\theta : X \rightarrow \mathbb{R}$, $Q^\phi : Y \rightarrow \mathbb{R}$
- For $\alpha \in S^1$, define

$$\forall (x, y) \in X \times Y, P^{\alpha, \theta, \phi}(x, y) = \alpha_1 P^\theta(x) + \alpha_2 Q^\phi(y)$$

- For $\mu, \nu \in \mathcal{P}_2(X \times Y)$,

$$SW_2^2(\mu, \nu) = \int W_2^2(P_{\#}^{\alpha, \theta, \phi} \mu, P_{\#}^{\alpha, \theta, \phi} \nu) d\lambda(\alpha, \theta, \phi)$$

- Sliced-Wasserstein on $\mathcal{P}_2(\mathbb{R}^d \times \mathcal{P}_2(\mathbb{R}^d))$ (SOTDD) (Nguyen et al., 2025)

- For a label $y \in \{1, \dots, C\}$, define $\varphi(y) = \frac{1}{n_y} \sum_{i=1}^n \delta_{x_i} \mathbb{1}_{\{y_i=y\}}$
- Use for $\alpha \in S^k$,

$$P^{\alpha, \theta, \lambda}(x, y) = \alpha_1 P^\theta(x) + \sum_{i=1}^k \alpha_{i+1} \mathcal{M}^{\lambda_i}(P_{\#}^{\theta} \varphi(y)),$$

with $P^\theta : \mathbb{R}^d \rightarrow \mathbb{R}$, $\mathcal{M}^\lambda : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$ the moment transform projection.

Previous Methods

- Sliced-Wasserstein on $\mathcal{P}_2(X \times Y)$ (Nguyen and Ho, 2024):

- Define 2 projections $P^\theta : X \rightarrow \mathbb{R}$, $Q^\phi : Y \rightarrow \mathbb{R}$
- For $\alpha \in S^1$, define

$$\forall (x, y) \in X \times Y, P^{\alpha, \theta, \phi}(x, y) = \alpha_1 P^\theta(x) + \alpha_2 Q^\phi(y)$$

- For $\mu, \nu \in \mathcal{P}_2(X \times Y)$,

$$SW_2^2(\mu, \nu) = \int W_2^2(P_{\#}^{\alpha, \theta, \phi} \mu, P_{\#}^{\alpha, \theta, \phi} \nu) d\lambda(\alpha, \theta, \phi)$$

- Sliced-Wasserstein on $\mathcal{P}_2(\mathbb{R}^d \times \mathcal{P}_2(\mathbb{R}^d))$ (SOTDD) (Nguyen et al., 2025)

- For a label $y \in \{1, \dots, C\}$, define $\varphi(y) = \frac{1}{n_y} \sum_{i=1}^{n_y} \delta_{x_i} \mathbb{1}_{\{y_i=y\}}$
- Use for $\alpha \in S^k$,

$$P^{\alpha, \theta, \lambda}(x, y) = \alpha_1 P^\theta(x) + \sum_{i=1}^k \alpha_{i+1} \mathcal{M}^{\lambda_i}(P_{\#}^{\theta} \varphi(y)),$$

with $P^\theta : \mathbb{R}^d \rightarrow \mathbb{R}$, $\mathcal{M}^\lambda : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$ the moment transform projection.

→ Use B^μ for projecting distributions on \mathbb{R}

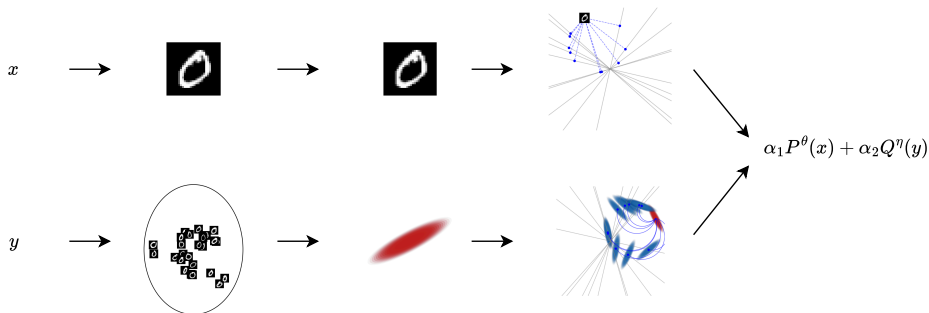
Slicing Datasets with Busemann on Gaussian

With Gaussian approximation:

- Define $\Xi(\mu) = \mathcal{N}(m(\mu), \Sigma(\mu))$
- For all $y \in \{1, \dots, C\}$,

$$Q^\eta(y) = B^\eta(\Xi(\varphi(y))),$$

with η a geodesic ray on $BW(\mathbb{R}^d)$



Computational Complexity: $O(LCd^3 + Ln_y C(\log n_y C + d) + d^2 C n_y)$

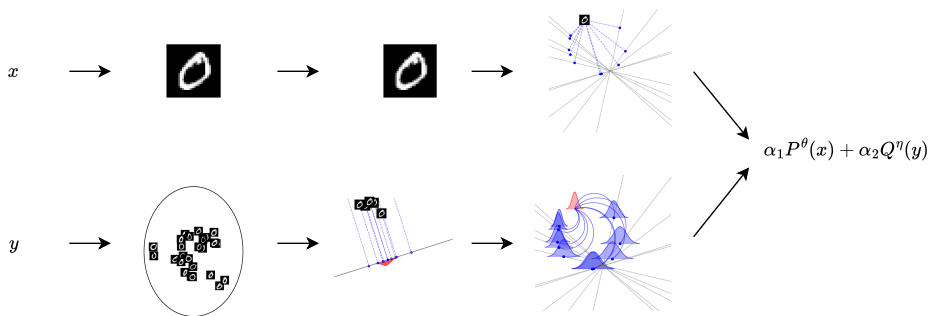
Slicing Datasets with Busemann in 1D

With 1D Projection:

- For all $y \in \{1, \dots, C\}$,

$$Q^{\eta, \theta}(y) = B^{\eta}(P_{\#}^{\theta} \varphi(y)),$$

with η a geodesic ray on $\mathcal{P}_2(\mathbb{R})$

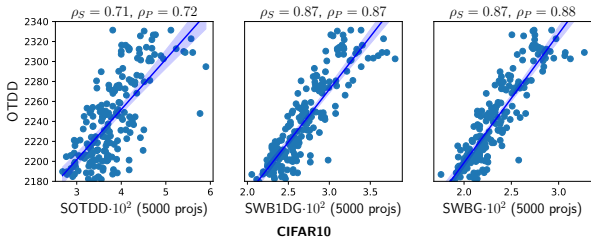
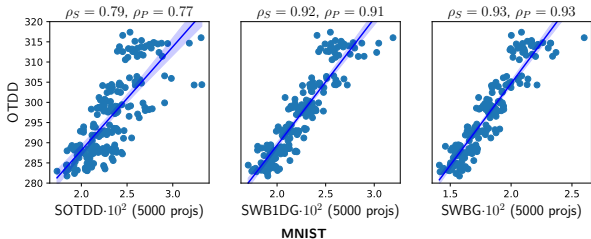


Computation Complexity: $O(Ln_y C(\log(n_y C + d)))$

Correlation vs OTDD

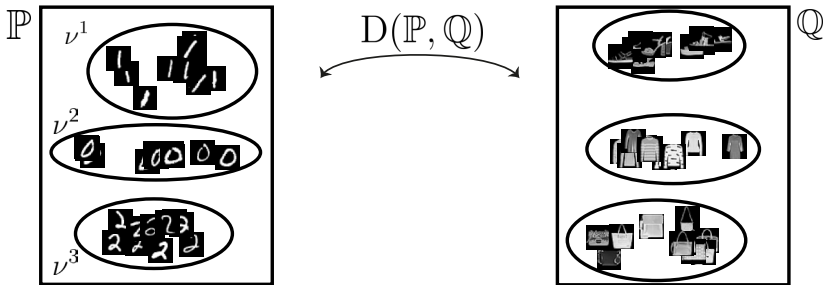
Goal: Measure correlation between sliced distances and OTDD

→ Compare randomly sampled subdatasets + Spearman and Pearson correlations



Flowing Labeled Datasets

- Model datasets as $\mathbb{P} = \frac{1}{C} \sum_{c=1}^C \delta_{\nu^c} \in \mathcal{P}_2(\mathcal{P}_2(\mathbb{R}^d))$ where $\nu^c = \frac{1}{n} \sum_{i=1}^n \delta_{x_i^c}$
 - Flow a dataset \mathbb{P} towards \mathbb{Q} by minimizing a discrepancy D on $\mathcal{P}_2(\mathcal{P}_2(\mathbb{R}^d))$
- minimization problem on $\mathcal{P}_2(\mathcal{P}_2(\mathbb{R}^d))$



Example

Let $\psi(\frac{1}{C} \sum_{c=1}^C \delta_{\mu^{n,c}}) = \frac{1}{nC} \sum_{c=1}^C \sum_{i=1}^n \delta_{(x_i^c, \mu^{n,c})}$ where $\mu^{n,c} = \frac{1}{n} \sum_{i=1}^n \delta_{x_i^c}$.

→ $D(\mathbb{P}, \mathbb{Q}) = \text{SWB1DG}(\mathbb{P}, \mathbb{Q})$

Minimizing on $\mathcal{P}_2(\mathcal{P}_2(\mathbb{R}^d))$ (Bonet et al., 2025b)

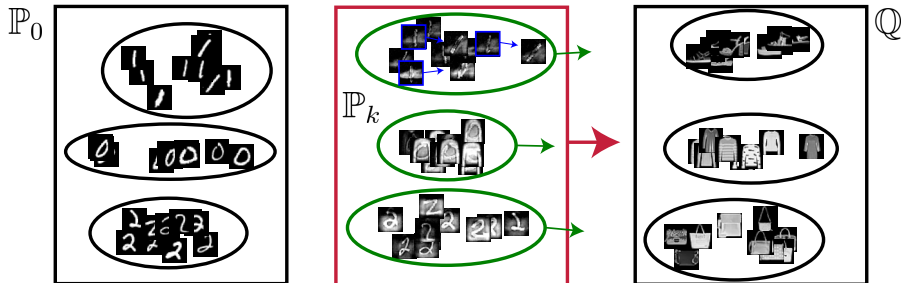
Goal: minimize $\mathbb{F} : \mathcal{P}_2(\mathcal{P}_2(\mathbb{R}^d)) \rightarrow \mathbb{R}$

In practice: For $\mathbb{P}_k = \frac{1}{C} \sum_{c=1}^C \delta_{\mu_k^{c,n}}$ with $\mu_k^{c,n} = \frac{1}{n} \sum_{i=1}^n \delta_{x_{i,k}^c} \in \mathcal{P}_2(\mathbb{R}^d)$:

$$\forall k \geq 0, \text{ particle (image) } i, \text{ class } c, x_{i,k+1}^c = x_{i,k}^c - \tau \nabla_{\mathbb{W}_{\mathbb{W}_2}} \mathbb{F}(\mathbb{P}_k)(\mu_k^{c,n})(x_{i,k}^c).$$

\mathbb{P}_k : inter-class interaction, $\mu_k^{c,n}$: intra-class interaction, $x_{i,k}^c$ image

$\nabla_{\mathbb{W}_{\mathbb{W}_2}} \mathbb{F}(\mathbb{P}_k)(\mu_k^{c,n})(x_{i,k}^c) = nC [\nabla F(\mathbf{x})]_{i,c}$ with $F(\mathbf{x}) = \mathbb{F}(\mathbb{P}_k)$, $\mathbf{x} = (x_{i,k}^c)_{i,c}$



Synthetic Data

Goal: minimize $\mathbb{F} : \mathcal{P}_2(\mathcal{P}_2(\mathbb{R}^d)) \rightarrow \mathbb{R}$

In practice: For $\mathbb{P}_k = \frac{1}{C} \sum_{c=1}^C \delta_{\mu_k^{c,n}}$ with $\mu_k^{c,n} = \frac{1}{n} \sum_{i=1}^n \delta_{x_{i,k}^c} \in \mathcal{P}_2(\mathbb{R}^d)$:

$\forall k \geq 0$, particle (image) i , class c , $x_{i,k+1}^c = x_{i,k}^c - \tau \nabla_{W_{W_2}} \mathbb{F}(\mathbb{P}_k)(\mu_k^{c,n})(x_{i,k}^c)$.

Let $\mathbb{Q} = \frac{1}{3} \sum_{c=1}^3 \delta_{\nu^c}$, ν^c ring

$$\min_{\mathbb{P}} \mathbb{F}(\mathbb{P}) = D(\mathbb{P}, \mathbb{Q})$$

SOTDD



SWB1DG



SWBG



Synthetic Data

Goal: minimize $\mathbb{F} : \mathcal{P}_2(\mathcal{P}_2(\mathbb{R}^d)) \rightarrow \mathbb{R}$

In practice: For $\mathbb{P}_k = \frac{1}{C} \sum_{c=1}^C \delta_{\mu_k^{c,n}}$ with $\mu_k^{c,n} = \frac{1}{n} \sum_{i=1}^n \delta_{x_{i,k}^c} \in \mathcal{P}_2(\mathbb{R}^d)$:

$\forall k \geq 0$, particle (image) i , class c , $x_{i,k+1}^c = x_{i,k}^c - \tau \nabla_{W_{W_2}} \mathbb{F}(\mathbb{P}_k)(\mu_k^{c,n})(x_{i,k}^c)$.

Let $\mathbb{Q} = \frac{1}{3} \sum_{c=1}^3 \delta_{\nu^c}$, ν^c ring

$$\min_{\mathbb{P}} \mathbb{F}(\mathbb{P}) = D(\mathbb{P}, \mathbb{Q})$$

SOTDD



SWB1DG



SWBG



Synthetic Data

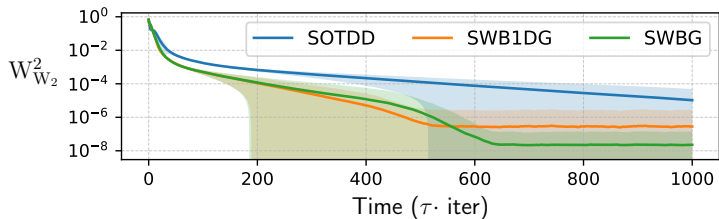
Goal: minimize $\mathbb{F} : \mathcal{P}_2(\mathcal{P}_2(\mathbb{R}^d)) \rightarrow \mathbb{R}$

In practice: For $\mathbb{P}_k = \frac{1}{C} \sum_{c=1}^C \delta_{\mu_k^{c,n}}$ with $\mu_k^{c,n} = \frac{1}{n} \sum_{i=1}^n \delta_{x_{i,k}^c} \in \mathcal{P}_2(\mathbb{R}^d)$:

$\forall k \geq 0$, particle (image) i , class c , $x_{i,k+1}^c = x_{i,k}^c - \tau \nabla_{W_{W_2}} \mathbb{F}(\mathbb{P}_k)(\mu_k^{c,n})(x_{i,k}^c)$.

Let $\mathbb{Q} = \frac{1}{3} \sum_{c=1}^3 \delta_{\nu^c}$, ν^c ring

$$\min_{\mathbb{P}} \mathbb{F}(\mathbb{P}) = D(\mathbb{P}, \mathbb{Q})$$



Conclusion

Conclusion:

- Studied geometry of geodesics on the Wasserstein space
- Studied the existence and computation of the Busemann function on the Wasserstein space
- Defined new SW distances to compare labeled Datasets
- Also in the paper: SW distances to compare Gaussian mixtures
- Related to new sliced distances on Gaussian mixtures ([Baouan et al., 2025](#); [Piening and Beinert, 2025a](#)) and on $\mathcal{P}_2(\mathcal{P}_2(\mathbb{R}^d))$ ([Piening and Beinert, 2025b](#))

Perspectives:

- Applications to PCA on the Wasserstein space
- Extension to $\mathcal{P}_2(\mathbb{L}^d)$
- Busemann along other curves ([Gallouët et al., 2025](#))

Thank you!

Paper: <https://arxiv.org/abs/2510.04579>



References I

- David Alvarez-Melis and Nicolo Fusi. Geometric Dataset Distances via Optimal Transport. *Advances in Neural Information Processing Systems*, 33: 21428–21439, 2020.
- Luigi Ambrosio, Nicola Gigli, and Giuseppe Savaré. *Gradient flows: in metric spaces and in the space of probability measures*. Springer, 2008.
- Ali Baouan, Mathieu Rosenbaum, and Sergio Pulido. An optimal transport based embedding to quantify the distance between playing styles in collective sports. *Journal of Quantitative Analysis in Sports*, 2025.
- Riccardo Bellazzi, Andrea Codegoni, Stefano Gualandi, Giovanna Nicora, and Eleonora Vercesi. The gene mover’s distance: Single-cell similarity via optimal transport. *arXiv preprint arXiv:2102.01218*, 2021.
- Paul Berg, Bjoern Michele, Minh-Tan Pham, Laetitia Chapel, and Nicolas Courty. Horospherical Learning with Smart Prototypes. In *British Machine Vision Conference (BMVC)*, 2024.
- Paul Berg, Léo Buecher, Björn Michele, Minh-Tan Pham, Laetitia Chapel, and Nicolas Courty. Multi-Prototype Hyperbolic Learning Guided by Class Hierarchy. *International Journal of Computer Vision*, pages 1–16, 2025.

References II

- Jérôme Bertrand and Benoît Kloeckner. A geometric study of Wasserstein spaces: isometric rigidity in negative curvature. *International Mathematics Research Notices*, 2016(5):1368–1386, 2016.
- Clément Bonet, Laetitia Chapel, Lucas Drumetz, and Nicolas Courty. Hyperbolic Sliced-Wasserstein via Geodesic and Horospherical Projections. In *Proceedings of 2nd Annual Workshop on Topology, Algebra, and Geometry in Machine Learning (TAG-ML)*, pages 334–370. PMLR, 2023.
- Clément Bonet, Lucas Drumetz, and Nicolas Courty. Sliced-Wasserstein Distances and Flows on Cartan-Hadamard Manifolds. *Journal of Machine Learning Research*, 26(32):1–76, 2025a.
- Clément Bonet, Christophe Vauthier, and Anna Korba. Flowing Datasets with Wasserstein over Wasserstein Gradient Flows. In *International Conference on Machine Learning*. PMLR, 2025b.
- Yann Brenier. Polar factorization and monotone rearrangement of vector-valued functions. *Communications on pure and applied mathematics*, 44(4):375–417, 1991.
- Martin R Bridson and André Haefliger. *Metric Spaces of Non-Positive Curvature*, volume 319. Springer Science & Business Media, 2013.

References III

- Herbert Busemann. *The Geometry of Geodesics*. Academic Press, New York, 1955.
- Ines Chami, Albert Gu, Dat P Nguyen, and Christopher Ré. HoroPCA: Hyperbolic Dimensionality Reduction via Horospherical Projections. In *International Conference on Machine Learning*, pages 1419–1429. PMLR, 2021.
- Julie Delon and Agnes Desolneux. A Wasserstein-Type Distance in the space of Gaussian Mixture Models. *SIAM Journal on Imaging Sciences*, 13(2):936–970, 2020.
- Lars Doorenbos, Pablo Márquez Neila, Raphael Sznitman, and Pascal Mettes. Hyperbolic Random Forests. *Transactions on Machine Learning Research*, 2024. ISSN 2835-8856.
- Xiran Fan, Chun-Hao Yang, and Baba Vemuri. Horocycle Decision Boundaries for Large Margin Classification in Hyperbolic Space. *Advances in neural information processing systems*, 36:11194–11204, 2023.
- Thomas O Gallouët, Andrea Natale, and Gabriele Todeschi. Metric extrapolation in the wasserstein space. *Calculus of Variations and Partial Differential Equations*, 64(5):147, 2025.

References IV

- Jonathan Geuter, Clément Bonet, Anna Korba, and David Alvarez-Melis. DDEQs: Distributional Deep Equilibrium Models through Wasserstein Gradient Flows. In *The 28th International Conference on Artificial Intelligence and Statistics*, 2025.
- Mina Ghadimi Atigh, Martin Keller-Ressel, and Pascal Mettes. Hyperbolic Busemann Learning with Ideal Prototypes. *Advances in Neural Information Processing Systems*, 34:103–115, 2021.
- Benoit Kloeckner. A geometric study of Wasserstein spaces: Euclidean spaces. *Annali della Scuola Normale Superiore di Pisa-Classe di Scienze*, 9(2):297–323, 2010.
- Matt Kusner, Yu Sun, Nicholas Kolkin, and Kilian Weinberger. From word embeddings to document distances. In *International conference on machine learning*, pages 957–966. PMLR, 2015.
- Khai Nguyen and Nhat Ho. Hierarchical Hybrid Sliced Wasserstein: A Scalable Metric for Heterogeneous Joint Distributions. *Advances in Neural Information Processing Systems*, 37:108140–108166, 2024.
- Khai Nguyen, Hai Nguyen, Tuan Pham, and Nhat Ho. Lightspeed Geometric Dataset Distance via Sliced Optimal Transport. In *Forty-second International Conference on Machine Learning*, 2025.

References V

- Moritz Piening and Robert Beinert. Slicing the Gaussian Mixture Wasserstein Distance. *Transactions on Machine Learning Research*, 2025a. ISSN 2835-8856.
- Moritz Piening and Robert Beinert. Slicing Wasserstein Over Wasserstein Via Functional Optimal Transport. *arXiv preprint arXiv:2509.22138*, 2025b.
- Julien Rabin, Gabriel Peyré, Julie Delon, and Marc Bernot. Wasserstein barycenter and its application to texture mixing. In *International Conference on Scale Space and Variational Methods in Computer Vision*, pages 435–446. Springer, 2011.
- Yossi Rubner, Carlo Tomasi, and Leonidas J Guibas. The Earth Mover's Distance as a Metric for Image Retrieval. *International journal of computer vision*, 40(2): 99–121, 2000.
- Luke Vilnis and Andrew McCallum. Word representations via gaussian embedding. In Yoshua Bengio and Yann LeCun, editors, *3rd International Conference on Learning Representations, ICLR 2015, San Diego, CA, USA, May 7-9, 2015, Conference Track Proceedings*, 2015.
- Guomin Zhu, Wen-Long Li, and Xiaojun Cui. Busemann functions on the wasserstein space. *Calculus of Variations and Partial Differential Equations*, 60 (3):97, 2021.